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TECHNICAL REPORT 4588

SPIN-73 AN UPDATED VERSION OF THE SPINNER COMPUTER PROGRAM

ROBERT H. WHYTE

NCVEMBER 1973

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Technical Report 4588

SPIN-73 AN UPDATFD VERSION OF THE SPINNER COMPUTER PROGRAM

by

Robert H. Whyte

November 1973

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Feltman Research Laboratory
Picatinny Arsenal
Dover, New Jersey 07801

under

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by

Armament Systems Department General Electric Co. Burlington, VT 05401

FOREWORD

This report documents tasks accomplished by the Armament Systems Department, General Electric Company, Burlington, Vermont under United States Government Contract No. DAAA21-73-C-0033 during the period from 14 August 1972 to 14 July 1973.

ACKNOWLEDGEMENT

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Branch of the Ballistic Research Laboratories, Aberdeen Proving Grounds;
the Aeroballistic Branch of Picatinny Arsenal; and the Aeroballistics Branch
(Range G) Arnold Engineering Development Center for their cooperation in
the collection and interpretation of data used in this study.

ABSTRACT

The SPINNER computer program has been updated to compute aerodynamic coefficients for a wide variety of spin stabilized projectile shapes.

Improvements over the original program are substantial as ogive radius, meplat diameter and rotating band diameter are accounted for instead of assuming mean values. Test cases are shown comparing the 1969 SPINNER, the 1973 SPINNER and experimental data. Input instructions and sample program outputs are given along with the 1973 program listing.

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NOMENCLATURE

Α	projectile cross-sectional area, ft ²
c_{1p}	spin deceleration coefficient, $M_{1p}/\bar{q}Ad(\frac{pd}{2V})$
C _m	pitching moment coefficient, $M_m/\bar{q}Ad$
C _m q	damping moment coefficient, $M_{m}/\bar{q}Ad(qd/2V)$
C _n p	magnus moment coefficient, $M_n / \overline{q} Ad(pd/2V)$
C _N	normal force coefficient, $F_N/\overline{q}A$
$C_{\mathbf{Yp}}$	magnus force coefficient, $F_{Yp}/\bar{q}A(pd/2V)$
c_{X}	axial force coefficient, $F_{X}/\bar{q}A$
CG	center of gravity, calibers from nose
τ _x	axial moment of inertia, slug-ft ²
^I y	transverse moment of inertia, slug-ft ²
$\mathbf{F}_{\mathbf{N}}$	normal force, 1bs.
$\mathbf{F}_{\mathbf{Yp}}$	magnus force, lbs.
$\mathbf{F}_{\mathbf{x}}$	axial force, 1bs.
M ₁ _p	spin damping moment
M _m	pitching moment about CG
M _m _Q	damping moment about CG
M _n _p	magnus moment about CG
V	total velocity, ft/sec.
d	projectile diameter, ft.
g	gravity, 32.174 ft/sec ²
m	projectile mass, slugs
P	projectile spin rate, radians/second
q	projectile pitch rate, radians/second

NOMENCLATURE (Continued)

 \overline{q} dynamic pressure, 1/2 ρ y^2 , 1b/ft² $\overline{\alpha}$ total angle of attack, radians ρ air density, slugs/ft³

Subscripts

α	Derivative	with	respect	to	$\sin \bar{\alpha}$
2	Derivative	with	respect	to	$\sin^2 \bar{\alpha}$
α ₃	Derivative	with	respect	to	$\sin^3 \bar{\alpha}$
ας	Derivative	with	respect	to	$\sin^5 \bar{\alpha}$

INTRODUCTION

The Armament Department of General Electric under contract to Picatinny Arsenal has developed an empirical computerized model for predicting the aerodynamic coefficients of spin stabilized projectiles. The code name of the new program is SPIN-73.

The starting point for the current study was the computer program 70° which was developed at Picatinny Arsenal during the period from September 1966 to October 1968. This program was modified by General Electric in 1969^{68} and 1970^{71} to update the predictions of the drag coefficient and also to perform a closed form dispersion analysis.

In general the method used during the development of the original Spinner was as follows:

Basic projectile configurations were selected which were considered by Whyte ^{68,70} to have well determined aerodynamic coefficients. Empirical equations and constants were developed, by a trial and error process, by which the standard coefficients could be adjusted for changes in total length, nose length, boattail length and center of gravity.

The following limitations were and are present in the original program.

- 1. Nose length 1.8 to 4.0 calibers
- 2. Projectile length 3.6 to 9.0 calibers
- 3. Boattail length 0.0 to 1.0 calibers
- 4. Meplot diameter, 0.10 to 0.15 calibers
- 5. Nose radius, secant +100% to secant -30%
- 6. Rotating band diameter, 1.025 calibers

^{*} References alphabetically listed starting on page 22.

However as most projectiles in service and under investigation during the period from 1966 to 1969 in general fell within the above bounds the limitations of the program were not considered very serious.

Since 1970 several programs have been initiated by the Army and Navy which are considering utilizing projectiles with nose lengths of up to 5.5 calibers and boattail lengths of up to 2.5 calibers.

Also payload and fuzing capabilities of several small arms projectiles currently under development by the Air Force, Navy, and Army have dictated blunter ogives (large meplats) and near tangent ogives.

Rotating band diameter are also of larger scale on small arms than corresponding shapes of large calibers thereby complicating the prediction process.

Because of these known limitations and future requirements the need for a revised SPINNER was indicated. Thus this current study was initiated in August 1972.

Sears 60 of Eglin in 1972 published a computerized curve fit technique for predicting the drag of projectile. His results indicated improvement over the original SPINNER in the area of tangent ogives and meplat bluntness.

A similar method to that used by Sears was employed in updating SPINNER. In discussing the computer programs the 1969 version of SPINNER will be referred to as SPIN-69 and the 1973 version as SPIN-73.

Chief Contract Contra

PROCEDURE

The most difficult task in the analysis of data is determining a constant accurate model which will adequately curve fit data under all circumstances, whereupon predictions of results under a different sets of initial conditions do not result in completely useless answers.

An example of useless results is shown in figure 15 where the predicted axial force is negative in the SPIN-69 program. When terms of higher order polynomials are employed to obtain good fits one must be very cautious when using these polynomials to extrapolate or even interpolate data. These cautions are pointed out because SPIN-73 does employ higher order polynomials.

The equations used for fitting and probable errors will be covered for each coefficient individually.

In general the data utilized with very fer exceptions was obtained from reports published by the Ballistic Research Laboratory (BRL) and Arnold Engineering Development Center (AEDC). No wind tunnel data was used at all in the data bank. Wind tunnel data was used to determine trends and comparisons were made with the trends resulting data fitting.

The references utilized to collect the experimental data are listed starting on page 22. Unpublished data from BRL, Picatinny, AEDC and GE were also used. The method used to curve fit the data is described briefly in Appendix A.

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Equations of the following general form were used for all coefficients. Definitions of VL, VN, VB, VCG, BD, DM, OR, and BOOM are found in figure 1.

$$C_{X} = a_{1} + a_{2} (CVN) + a_{3} (CVN^{2})$$

$$+ a_{3} (CXCL) + a_{4} (CXCL^{2})$$

$$+ a_{5} (CVN \cdot CXCL)$$

$$+ a_{6} (CVB) + a_{7} (CBD)$$

$$+ a_{8} (CMK) + a_{9} (CMK^{2})$$

$$+ a_{10} (CVN \cdot CMK) + a_{11} (CXCL \cdot CMK)$$

$$+ a_{11} (CRAT) + --- \text{ etc.}$$

where:

$$CVN = VN - 2.5$$

$$CXCL = VL - VN - VB - 1.5$$

$$CVB = VB$$

$$CBD = BD - 1.02$$

$$CMK = CMK - 1.05$$

$$CRAT = VN^{2}/OR - 0.40$$

The combinations, variations, and parameters which can be included in the fitting equation are nearly infinite. References such as Dickenson, $^{19-28}$ Sears, 60 Watt, 66 and Murphy 43 were used as guides for determining the most effective way of deriving an empirical equation. By the trial and error process equations of the above type were manipulated into a form which adequately described the experimental data.

EMPIRICAL EQUATIONS

This section will describe individually for each coefficient the equations contained in the computer program SPIN-73 as of June 1973.

Axial Force Coefficient

$$CXCL = VL - VN - VB - 1.5$$

$$CBD = DB - 1.02$$

$$CDM = (DM - 0.12)^{2} \qquad CRAT = VN^{2}/OR - 0.40$$
if 0 < VN < 3.0 set VNX = VN , DXN = 0.0
if 0 < CXCL < 1.5 set CXCLL = CXCL , DXCL = 0.0
if 0.2 < VB < 0.65 set VBX = VB - 0.2 DXBT = 0.0

If VN, CXCL, or VB are greater than the maximum

set
$$VNX = 3.0$$
, $DXN = (VN - 3.0)$ A_{13}

$$CXCLL = 1.5$$
, $DXCL = (CXCL - 1.5)$ 0.01
$$VBX = 0.45$$
, $DXBT = (VB - 0.65)$ A_{10}

If VB is less than the minimum

$$VBX = 0.0$$
 , $DXBT = 0.0$

$$C_X = a_1 + a_2 (VNX - 2.5) + a_3 (VNX - 2.5)^2$$

+ $a_4 (VNX - 2.5)^3 + a_5 (CXCLL) + a_6 (CXCLL)^2$
+ $a_7 (VBX) + a_8 (CRAT) + a_9 (CRAT)^2$
+ $a_{11} (CBD) + a_{12} (CDM) - (BOOM/1.36,^2 0.01$
- DXBT - DXN + DXCL

The "IF" statements are required to circumvent the need for higher order polynomials in the equations. In this manner only linear extrapolation and interpolations are allowed on the fringes of the program capabilities. This should prevent completely erroneous estimates.

Normal Force Coefficient Derivative, Pitching Moment Coefficient Derivative and Normal Force Center of Pressure

if
$$0 < VN < 3.0$$
 set $VNX = VN$, $DNX = 0.0$
if $0 < VB < 1.0$ set $VBNP = VB^A$, $VBMP = VB^B$, $VBX = VB$
where: Subsonic A = 1.0, B = 0.8
Supersonic A = 1.5, B = 1.0

if $\ensuremath{\text{VN}}$ or $\ensuremath{\text{VB}}$ are greater than the maximum

set VNX = 3.0 , DNX = VN - 3.0
$$VBX = 1.0 , VBNP = VB^{0.5} , VBMP = VB^{0.5}$$

Now set

CVNN = VNX - 2.47
CXLL = VL - VN - VB - 2.15
CDMM = DM - 0.17
CBBD = BD - 1.04
CCRT =
$$VN^2/OR - 0.48$$

VBT1 = $CVL/4.7$

$$\begin{array}{l} \text{CNAB} = \text{B}_1 + \text{B}_2 \quad (\text{CVNN}) + \text{B}_3 \quad (\text{CXLL}) + \text{B}_4 \quad (\text{CCRT}) + \text{B}_5 \quad (\text{CVNN})^2 + \text{B}_6 \quad (\text{CXLL})^2 \\ \text{CNBT} = \text{B}_7 \quad (\text{VBNP}) + \text{B}_8 \quad (\text{VBX} \cdot \text{CVNN}) + \text{B}_9 \quad (\text{VBX} \cdot \text{CXLL}) \\ \text{CNAT} = \text{CNAB} + \text{CNBT} \\ \end{array}$$

AMOMSQ = CNAB
$$[C_1 + C_2 (CVNN) + C_3 (CVNN)^2 + C_4 (CVNN)^3 + C_5 (CXLL) + C_6 (CXLL)^2 + C_7 (CXLL)^3 + C_8 (CCRT) + C_9 (CCRT)^2 + C_{10} (CDMM) + C_{11} (CCRT \cdot CYNN) + C_{17} (DNX)]$$

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AMOMBT = VBTT
$$[C_{12} \text{ (VBMP)} + C_{13} \text{ (VBX } \cdot \text{ CVNN)}]$$

+ $C_{14} \text{ (VBX } \cdot \text{ CXLL)} + C_{15} \text{ (VBX } \cdot \text{ CCRT)}$
+ $C_{16} \text{ (VBX } \cdot \text{ CCRT } \cdot \text{ CVNN)}]$

$$CPN = (AMOMSQ + AMOMBT)/CNAT$$

$$C_{N_{\alpha}} = CNAT$$
 $C_{M_{\alpha}} = (VCG - CPN) C_{N_{\alpha}}$

Yaw Axial Force Coefficient

$$CXCL = VL - VN - VB - 1.5$$

$$CRAT = VN^{2}/OR - 0.40$$

$$CVB = VB$$

$$C_{X_2} = D_1 + D_2$$
 (CXCL) + D_3 (CRAT) + D_4 (CVB) - $C_{N\alpha}$

The Yaw Drag coefficient may be computed by adding C_{X_2} and $C_{N\alpha}$.

Magnus Force Coefficient Derivative, Magnus Moment Coefficient Derivative, Magnus Force Center of Pressure

$$CVL = VL$$

$$CVB = VB$$

$$CXCL = VL - VN - VB - 1.5$$

$$CVN = VN - 2.5$$

$$CYPA = E_1 (CVL) - 0.1 (CVB)$$

at $\overline{\alpha} = 1.0^{\circ}$

CNPAN =
$$-E_1$$
 (CVL) [$E_2 + 0.55$ (CXCL) + 0.80 (CVN)]
+ CVB (CVL/4.7)

$$CPF_{(1)} = -CNPAN/CYPA$$

$$C_{Yp\alpha} = CYPA$$

$$C_{n_{p\alpha}(1)} = (VCG - CPF_{(1)}) C_{Yp\alpha}$$

at $\bar{\alpha} = 2.0^{\circ}$

CNPAN =
$$-E_1$$
 (CVL) [$E_3 + 0.55$ (CXCL) + 0.80 (CVN)]
+ CVB (CVL/4.7)

$$CPF_{(2)} = -CNPAN/CYPA$$

$$C_{yp\alpha} = CypA$$

$$c_{n_{p\alpha}(2)} = (VCG - CPF_{(2)}) c_{yp\alpha}$$

at $\bar{\alpha} = 5.0^{\circ}$

$$CNPAN = -E_{J}$$
 (CVL) $[E_{4} + 0.55$ (CXCL) + 0.80 (CVN) + CVB (CVL/4.7)
 $CPF_{(5)} = -CNPAN/CYPA$

$$c_{Yp\alpha} = CYPA$$

$$c_{n_{p\alpha}(5)} = (VCG - CPF_{(5)}) c_{Yp\alpha}$$

Damping Moment Coefficient

$$CLL = VL - 5.0$$

$$CCG = VCG - 3.0$$

CVB = VB

$$C_{m_q} = -5.093 [F_1 + F_2 (CLL) + F_3 (CLL^2) + F_4 (CCG) + F_5 (CCG) (CLL) + F_6 (CCG) (CLL^2) + F_7 (CCG) (CVB) + F_8 (CVB)]$$

Spin Deceleration Coefficient

$$c_{1_p} = G1 \ (VL/5.51)$$

Stability Analysis

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The methods used for stability computations were extracted from references 44 and 45. They are identical to those contained in the original SPINNER.

Gyroscopic Stability Factor,
$$s_g$$

$$s_g = 2I_x^2 p^2 / \pi I_{yp} C_{m_{qq}} d^3 V^2$$

Dynamic Stability Factor, s_d

$$s_{d} = \frac{2(C_{N_{\alpha}}^{-C_{X}} + (k_{1}^{-2}/2) C_{n_{p\alpha}})}{(C_{N_{\alpha}}^{-C_{X}} - (k_{2}^{-2}/2) C_{m_{q}} + (k_{1}^{-2}/2) C_{1_{p}})}$$

Nutation, Precession Frequencies $\omega_{1,2}$

$$\omega_{1,2} = \frac{pI_x}{2I_y} \quad (1 \pm \sigma)$$

Nutation, Precession Yaw Damping Rates, $\lambda_{1,2}$

$$\lambda_{1,2} = \frac{\rho A}{4m} \left[-c_{N_{\alpha}} \left(1 \pm \frac{1}{\sigma} \right) + (k_2^{-2}/2) \left(1 \pm \frac{1}{\sigma} \right) c_{m_q} \pm (k_1^{-2}/\sigma) c_{n_{p\alpha}} \right]$$

where

$$k_1^{-2} = md^2/I_x$$

$$k_2^{-2} = md^2/I_y$$

$$\sigma = \sqrt{1 - 1/s_g}$$

The dispersion (DISP) is the radius in mils of a circle which a projectile will impact in a vertical plane when disturbed to a first maximum yaw angle of 5 degrees or less. The basis for this calculation is derived in Reference 71.

The time step (DELT) shown will provide 20 integrations per nutation cycle. This is entirely adequate for a 4th Order Range Kutta integrator.

RESULTS AND DISCUSSIONS

The results of several test cases are presented in Figures 2 thru 15. Plotted are experimental points, SPIN-69 and SPIN-73 results. Tabulated outputs of SPIN-73 are shown as tables 2 thru 15.

The following ranges of parameters are demonstrated by the test cases.

Total length 3.8 thru 10.0 calibers

Nose length 1.6 thru 5.5 calibers

Boattail length 0.0 thru 1.0 calibers

Ogive radius tangent thru conical

Meplat diameter 0.0 thru 0.26 calibers

Band diameter 1.00 thru 1.05 calibers

In general the correlations between SPIN-73 and the experimental data is very good with noticeable improvements over SPIN-69. Most of the effort during this current study has been directed at the Axial Force and Pitching Moment correlations as these two coefficients are by far the most accurately determined during the experimental process. Much work still remains to be done on these coefficients in terms of defining a more adequate empirical model.

The most poorly determined coefficients remain the Magnus and damping. It is this author's opinion that the SPIN-73 improvement in these the calculations is negligible. While some new data has been published since 1968, in general data was previously available on similar shapes. For example the projectiles referred to as the XM380 and XM549 were experimentally

investigated long ago as the T388 and T387. This data was available in 1967 and had been included in the original (SPIN-69) program.

The bulk of the data published by AEDC through calendar year 197? is suspect as far as the Magnus and damping coefficient are concerned because the effect on linear theory reductions of a slowly varying pd/2V was not taken into account.

This author also found in several instances as did Sears that the geometric description of the projectiles under test were not available either in the data reports or the data files.

The probable errors to the experimental data of the SPIN-73 empirical equations are shown in Table 1. The number of data points used to compute the probable error is shown in parenthesis.

CONCLUSIONS AND RECOMMENDATIONS

The SPIN-73 program has been shown through test cases to be more accurate than the SPIN-69 program.

The updating of SPIN-73 should be continued as new data is accumulated. Records should be kept of shortcomings and extremely poor predictions.

Data should be more carefully reported with respect to actual configuration tested.

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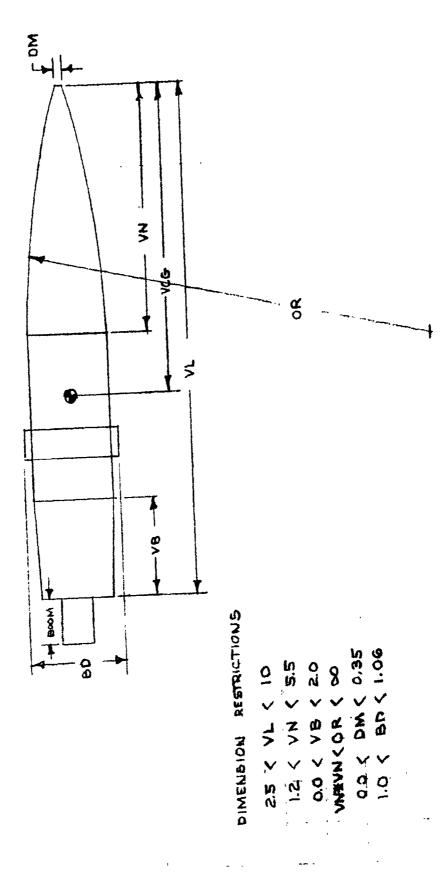
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PROJECTILE PARAMETERS - INPUT/OUTPUT

TABLE 1

e _{Cx}	SQ BASE	CONTAIL BONTAIL	SOR BEE	ecm	ecmg	ورسهم
00	0.0 6 (86)	0.10	(90)	9.18 (88)	3.0	0.18 (72)
05	०० (८६)	0.10	0.15 (90)	0.11 (39)		
0 8	0.06	o. : : : (§)	0.15 (90)	0,12 (53)		0.16 (72)
0.5	0.09	0.10	(138)	0.10	3.0 (78)	
60.0 (e2i)	୭.କ	9.10	0.13	0.10		0.76 (72)
0.09	ଚ୍ଚ	60°3	(9E)	4.0 (%)		0.72 (59)
(621)	96	0.08 (52)	0.13 (138)	0.15	3.0	0.12 (59)
0.09 (132)	8 (g	0.07 (50)	0.12	0.17	3.0 (63)	0.12 (53)
0,09 (132)	0,09 (132)	0.06 (38)	0.12 (141)	0.17		0.1 2 (59)
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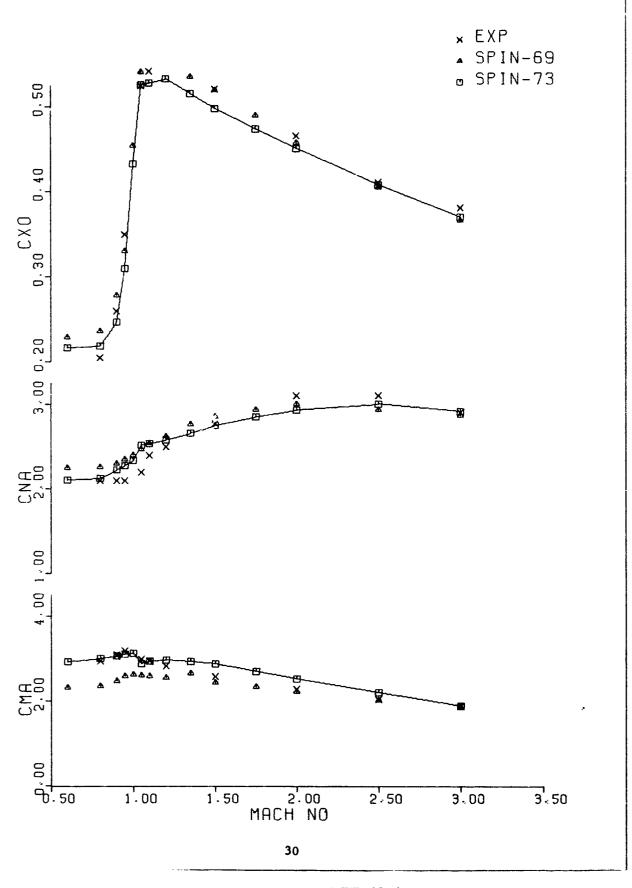
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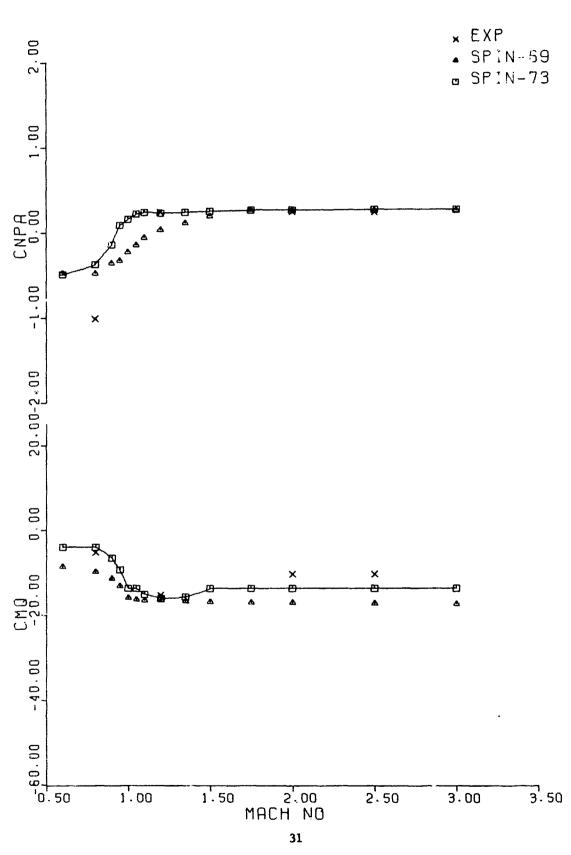
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	~ c	## ###################################		Cheses	0.103	101	0.254	0.120	2.4.0	4.4.4	848.0	0.355	0.319	0.315	0.335	0.319	0.315	0.539	0.315	6.33	0.315
	MOSE Padius 10.000	100		50103	2.476	2.476	2.678	3.796	2.776	9.776	2.774	9.116	2.176	7.774	2,776	2,776	7,778	7.776	2.176	2.776	2.776
		######################################		(Jd)	1.476	1.476	1.676	2.078	2.13	2.478	2.37	7.676	4.4.4	7.4.4	2.616	7.694	2.706	7,716	7.73	2.726	2.736
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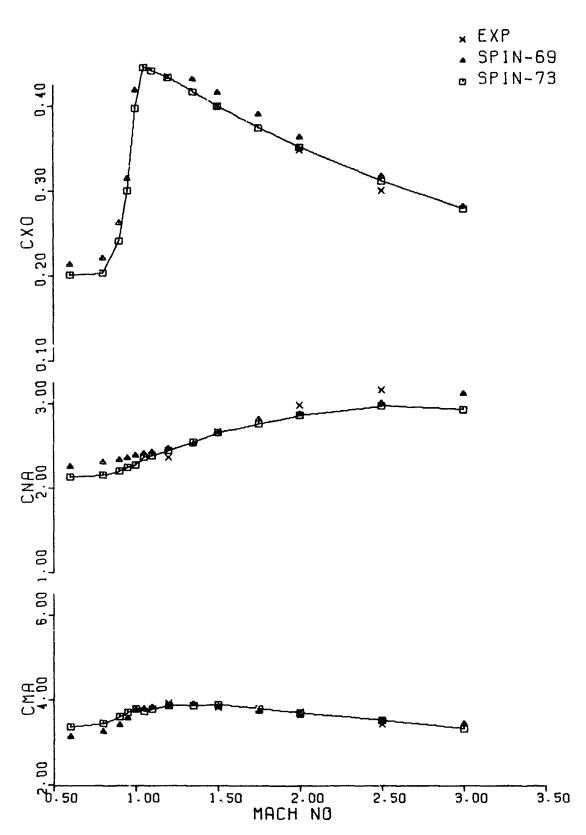
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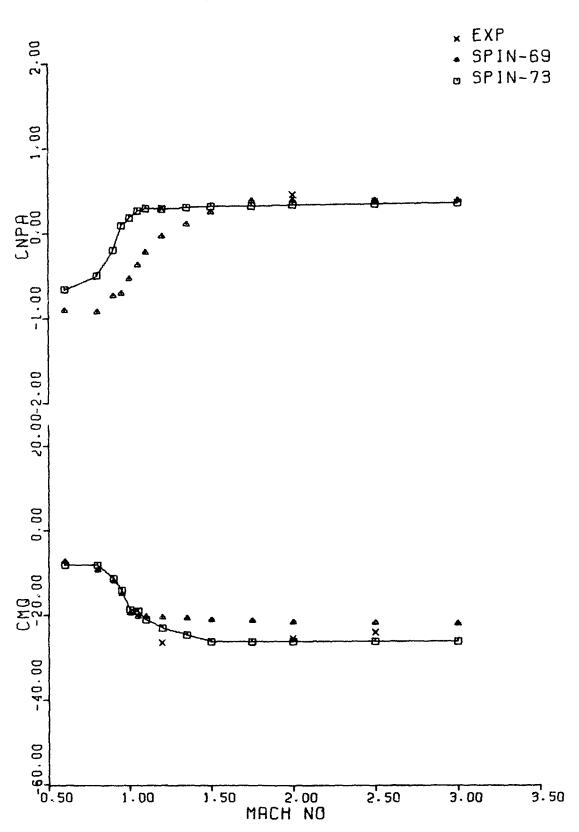
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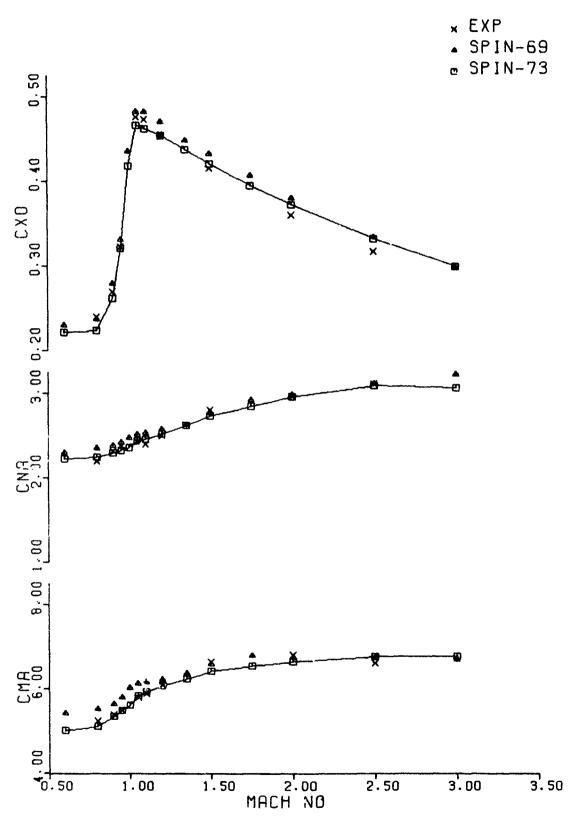
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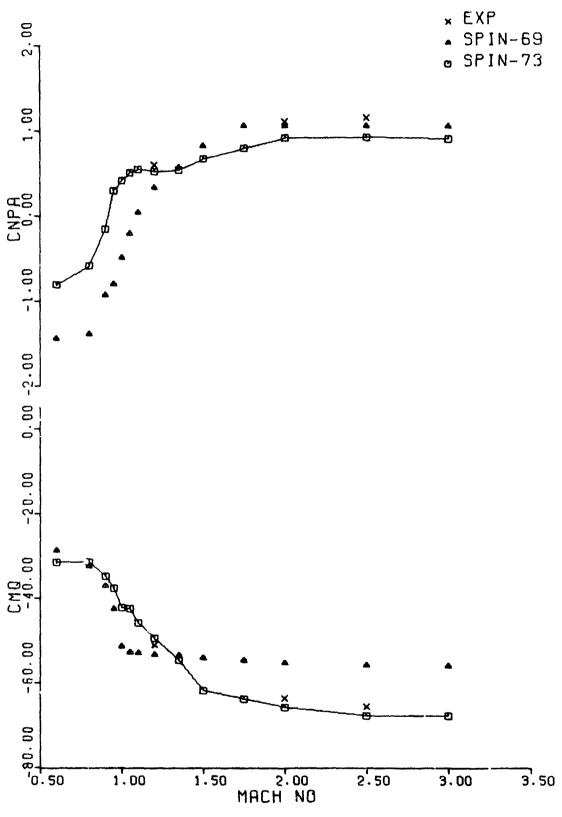
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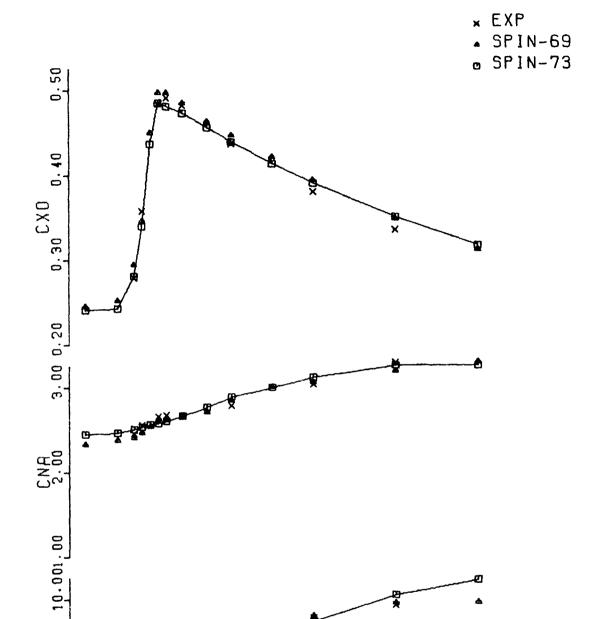


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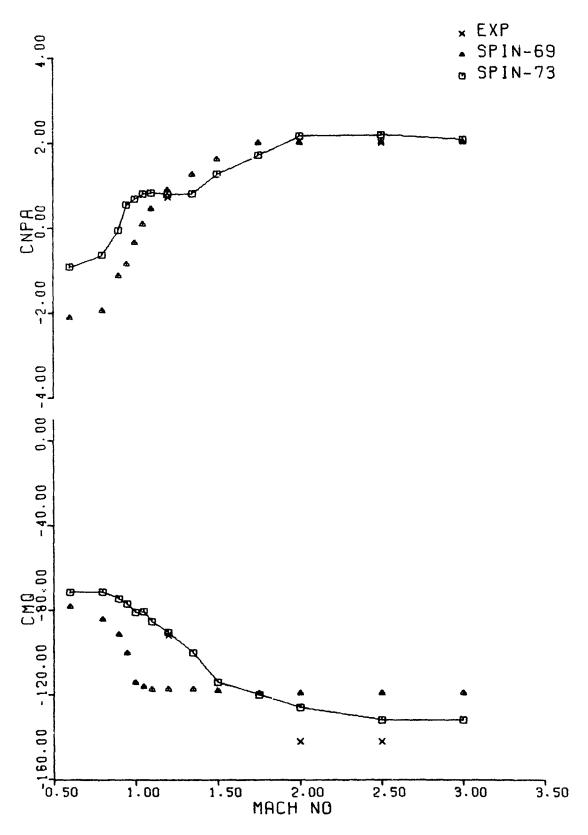
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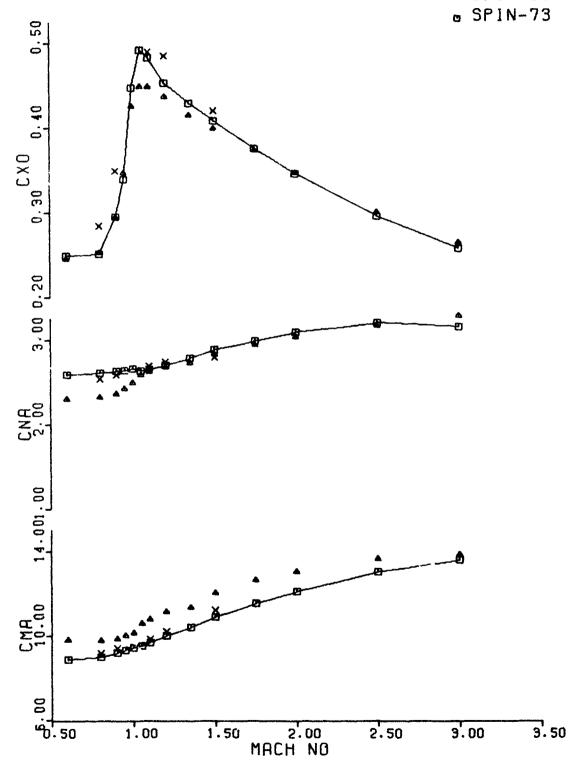


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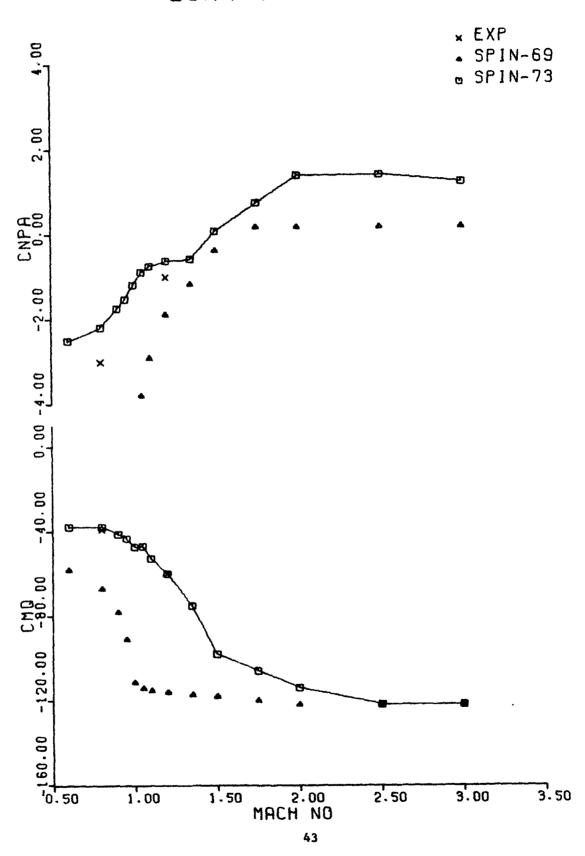
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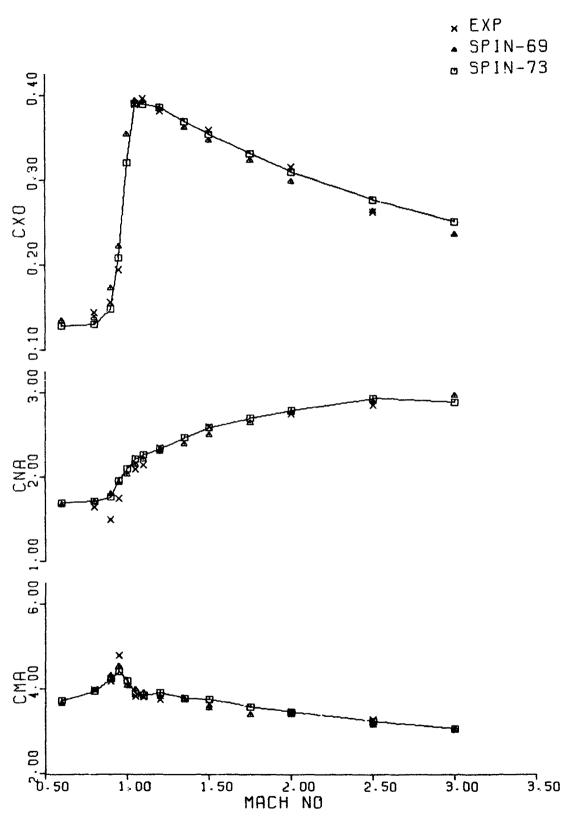


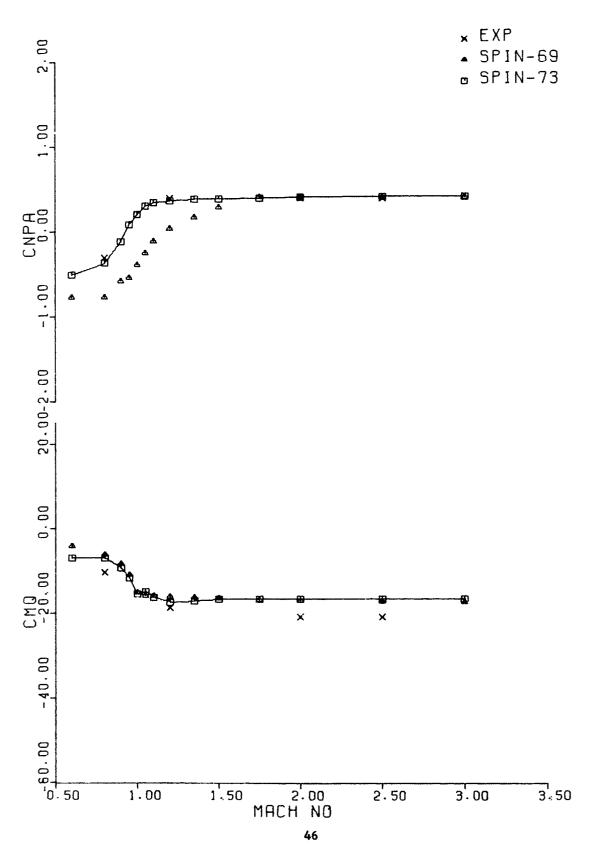
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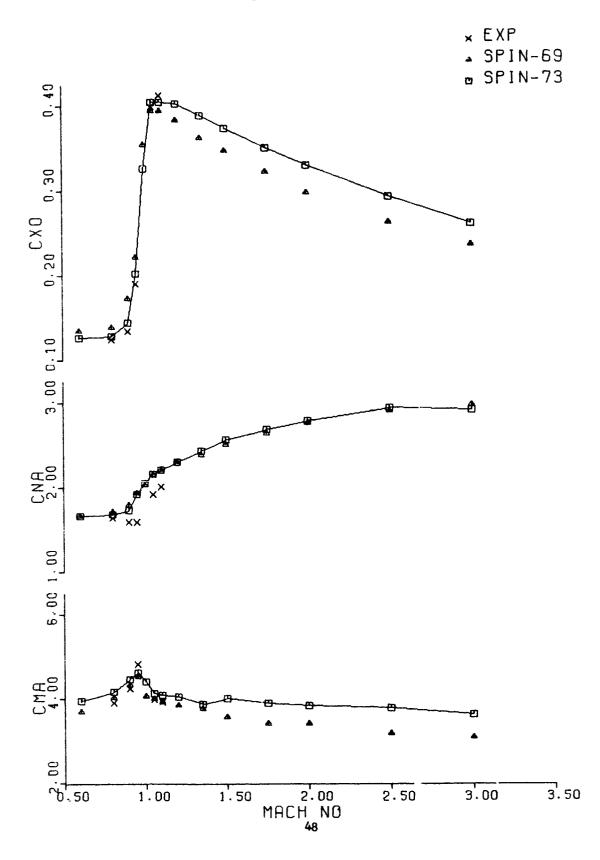


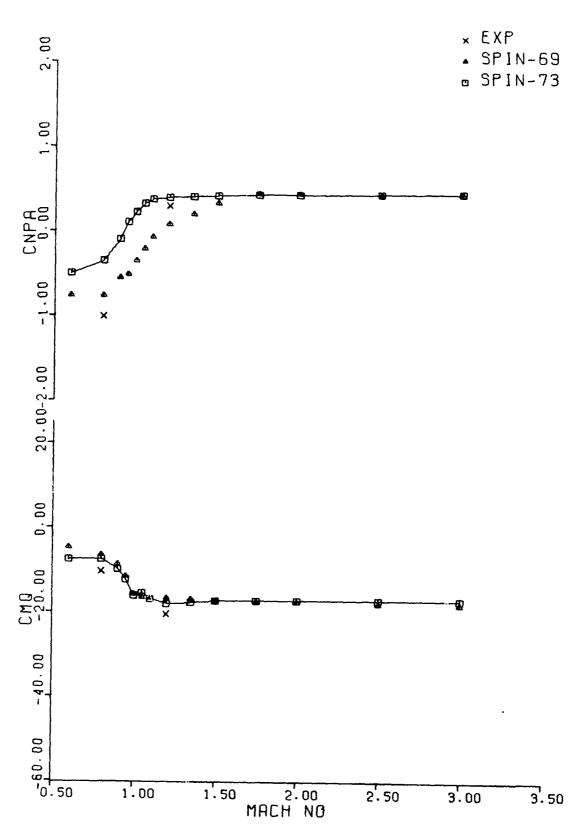


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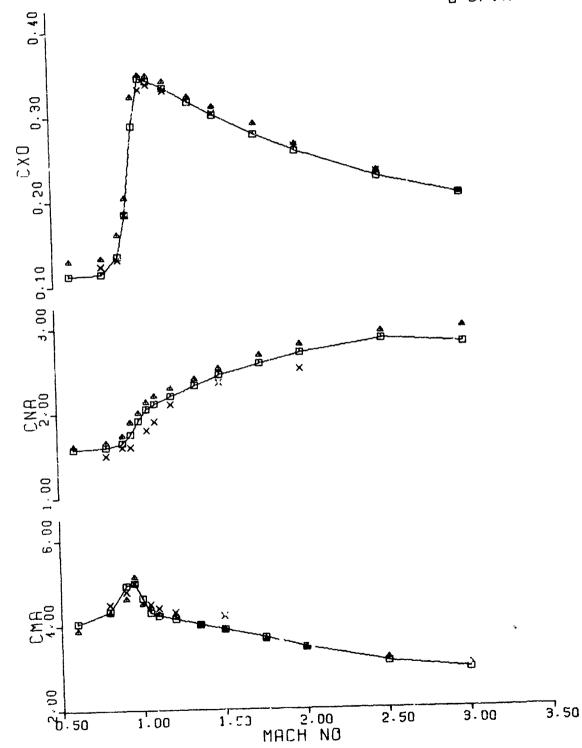
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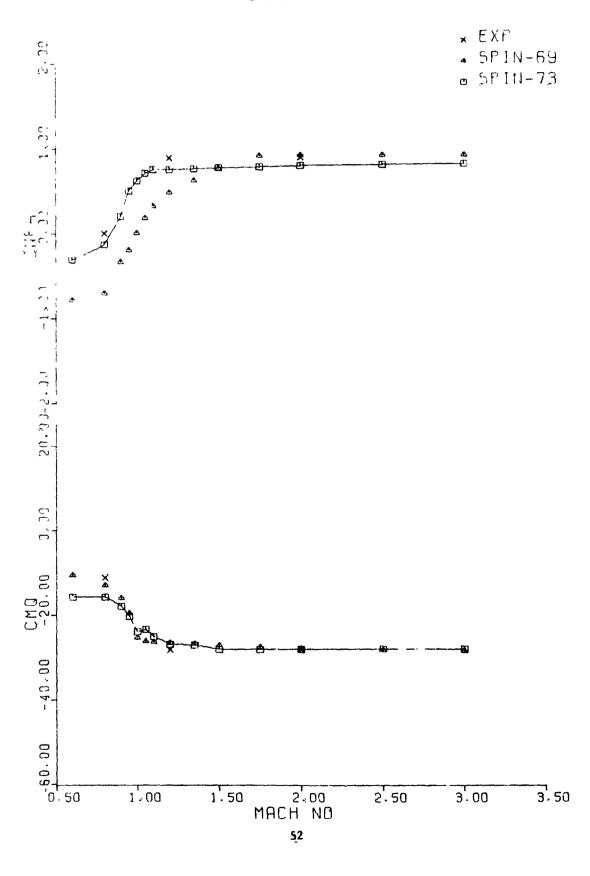
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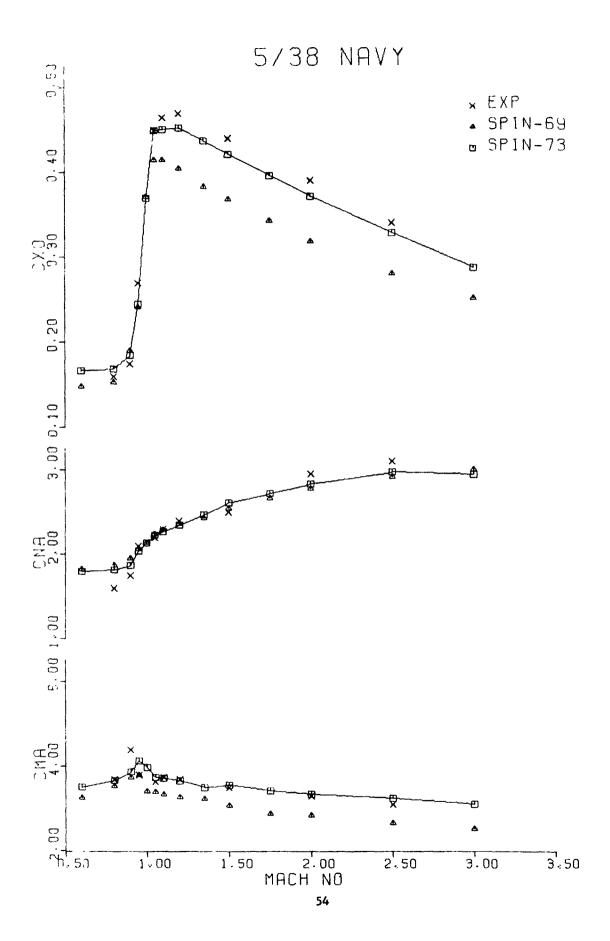
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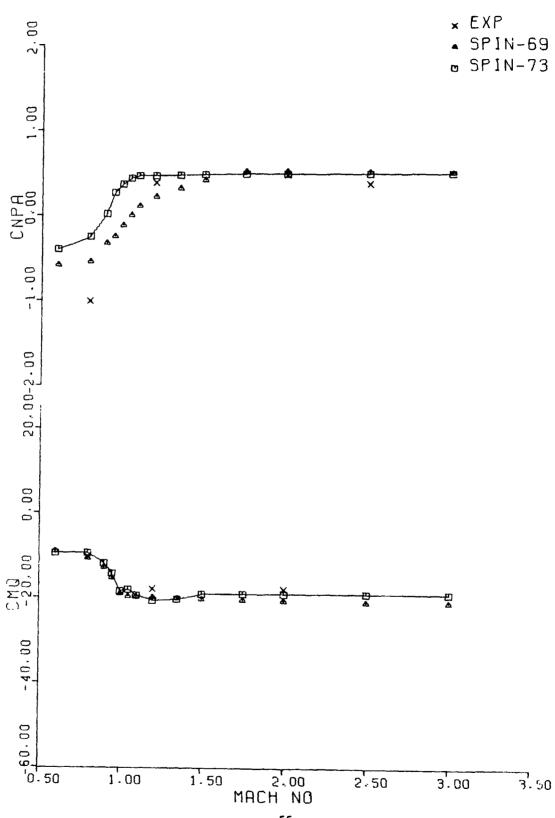
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5/38 NAVY

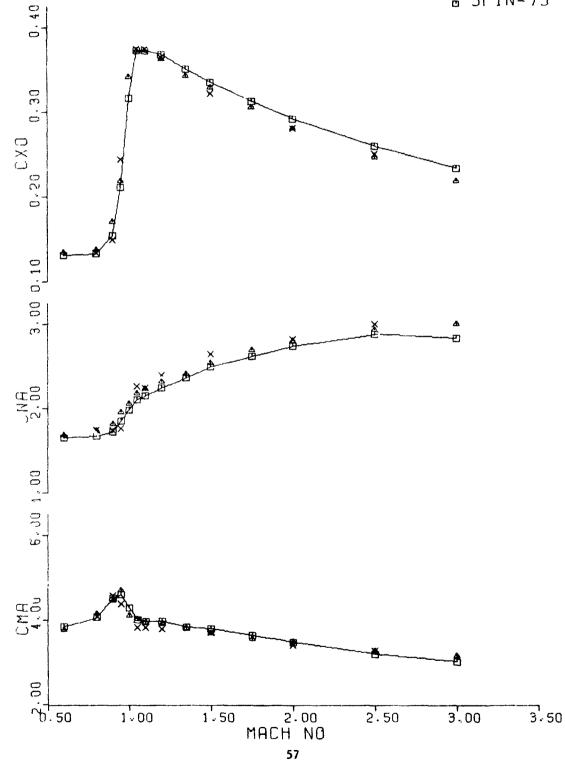


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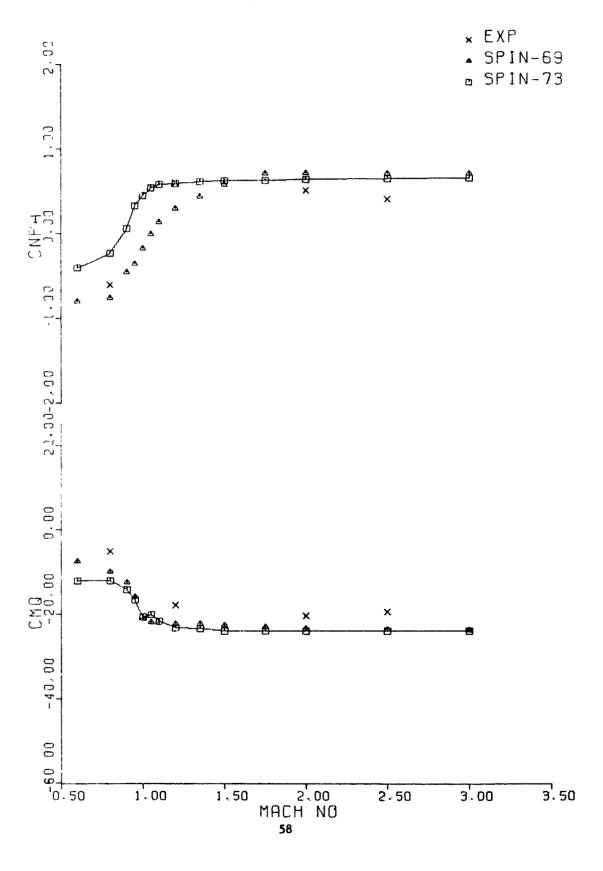
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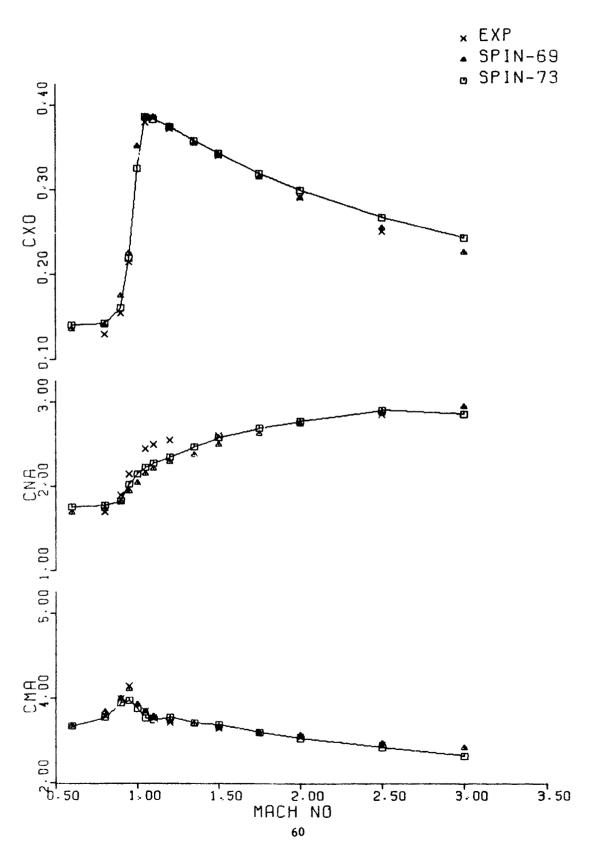


5/54 NAVY

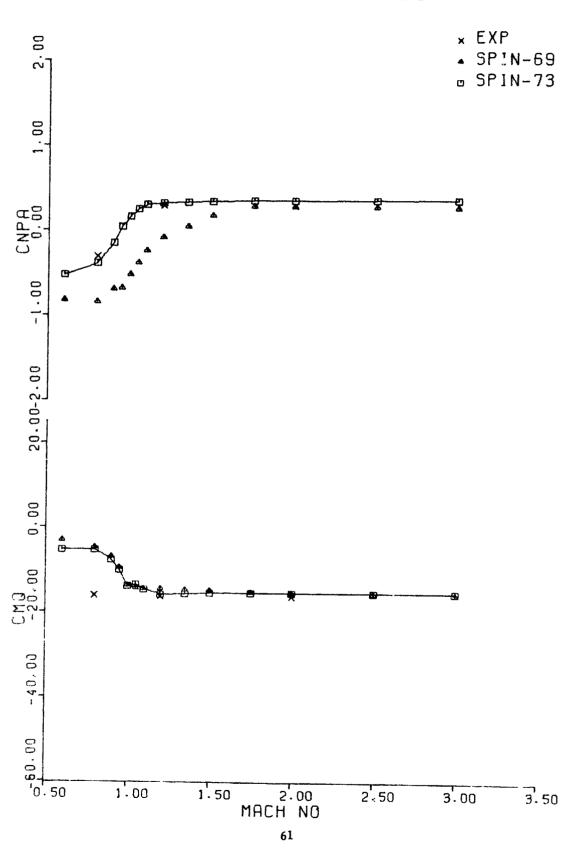


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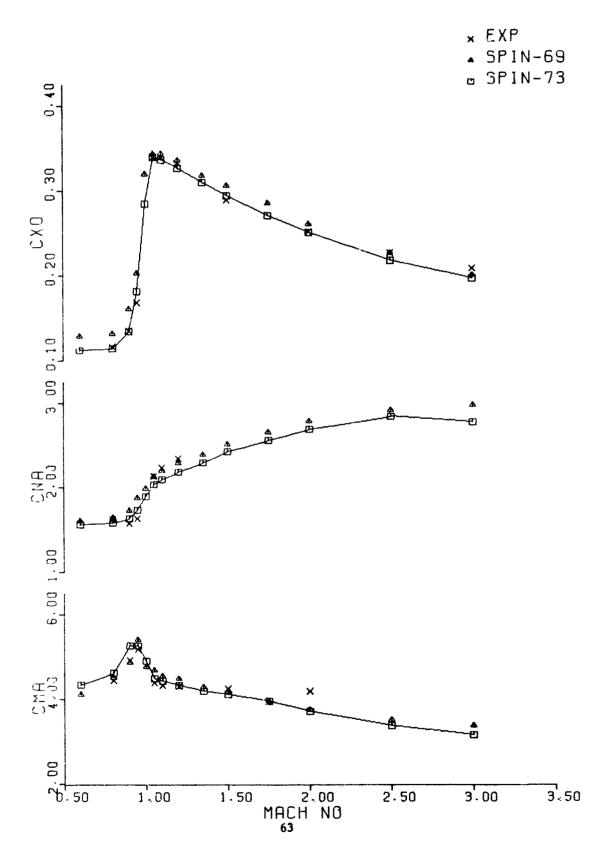
155MM M101/107

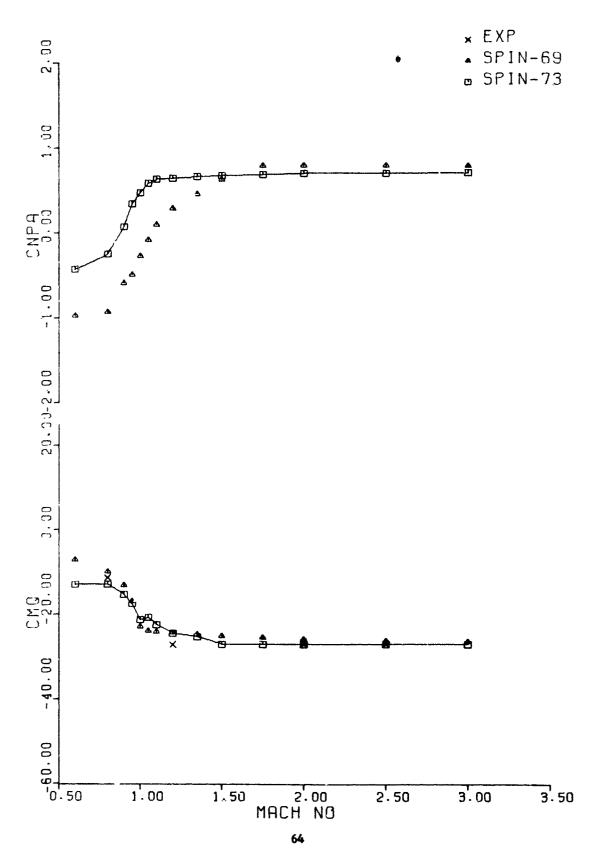


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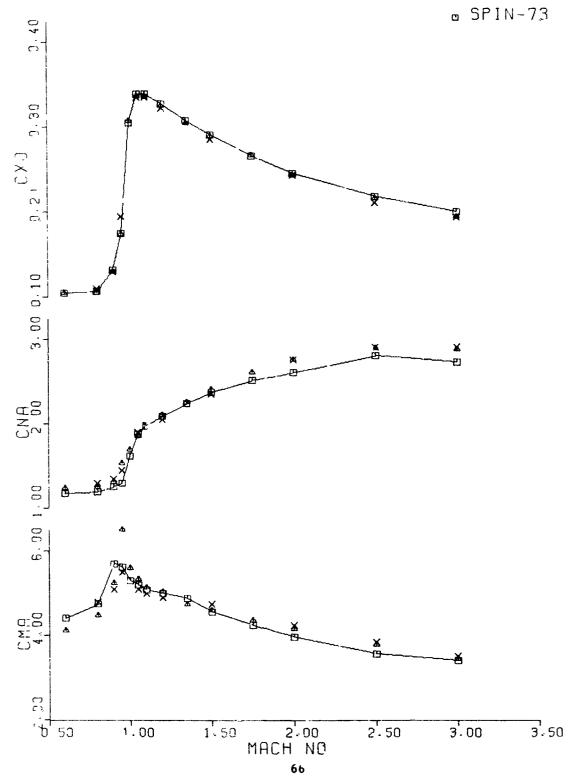


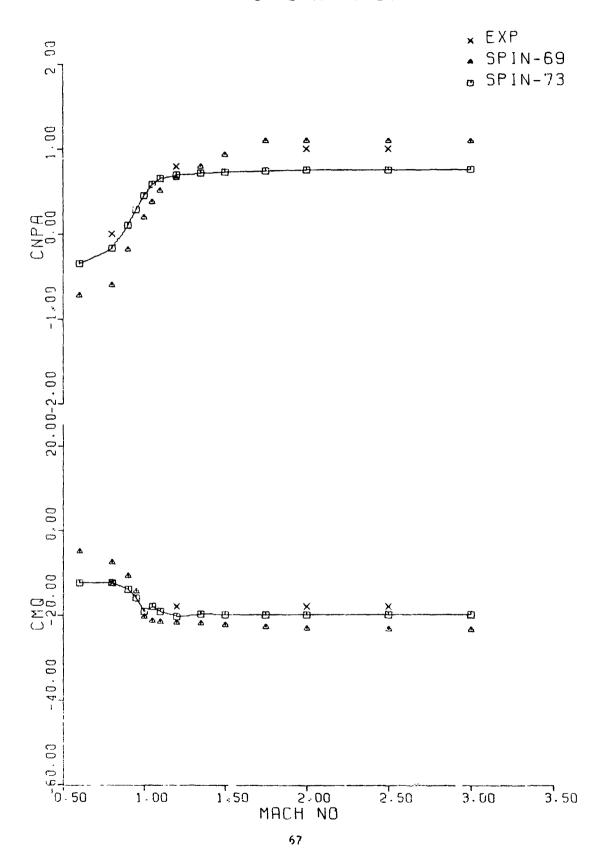
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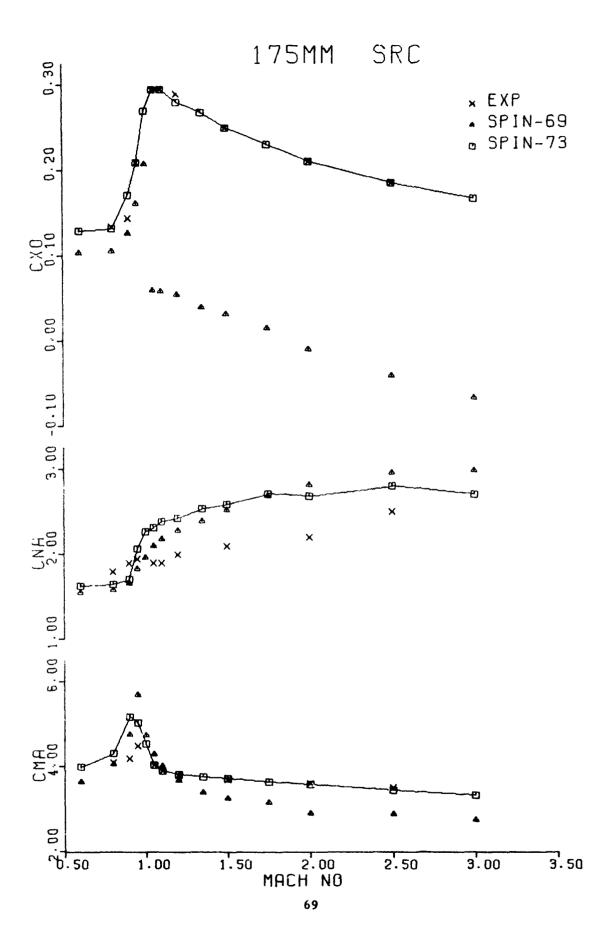
SPIN-69



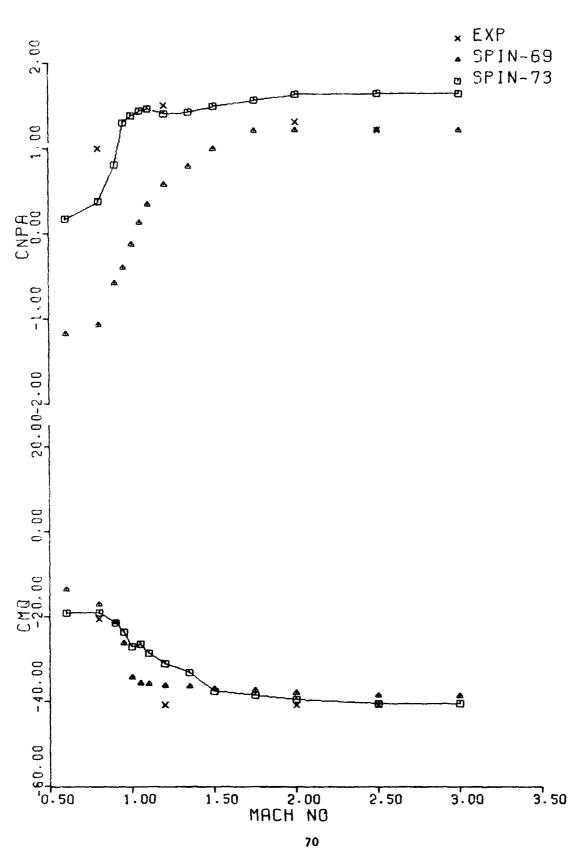


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APPENDIX A

CURVE F1T TECHNIQUE

CURVE FIT TECHNIQUE

The method used to perform least squares fits to the experimental data using the empirical equations was a GE Time Sharing computer program code name LSQMM. This program was utilized with the GE415 computer at the Armament Systems Department. The brief description starting or the next page of this program was extracted from the following reference.

Numerical Analysis Routines #807231A Information Service Department General Electric Company Bethesda, Maryland

Issued August 1968 (Revised Feb. 1969)

LSQMM

This routine determines the coefficients A(J), J=1,2,...N of the function

$$\mathbf{F}(\mathbf{I}) = \mathbf{A}_1^{\mathbf{Q}}_{\mathbf{I},1} + \mathbf{A}_2^{\mathbf{Q}}_{\mathbf{I},2} + \ldots + \mathbf{A}_n^{\mathbf{Q}}_{\mathbf{I},n} \qquad \mathbf{I} = 1,2,\ldots,M$$

which determines the best approximation of the function Y(I) in either the weighted least squares sense or the min-max sense.

Usage

The calling sequence for this routine is:

CALL LSQMM(PI') Y.A.RW, M.N.NT, NS, AM, IDIMM, IDIMN)

where,

- PHI is the two immensional array, PHI(M,N), of coordinate functions which are supplied by the above. The kth column of PHI contains the kth coordinate function evaluated at each of the data points (i.e., PHI(I,k), I = 1,2,..., M).
- Y is the one dimensional array, Y(M), containing the dependent variables.
- A is the one dimensional array, A(N).
- The A array contains the coefficients A(J) of the function F(I).
- RW is the name of an array containing the residuals R(I) Y(I)-F(I), the weights W(I), and temporary storage to save the vertical weights while doing the horizontal iterations. It should contain at least 3*M locations.
- M is the number of data points.
- N is the number of coefficients, i.e., number of coordinate functions,
- NT is the maximum number of vertical iterations. For least squares fit, NT = 1.
- For least squares fit and when there is no division of the data points in min-max., NS(1) = M. Otherwise, NS is the array containing the index values of the ends of the sections when using min-max fit;
- AM is a two dimensional array, AM(N,N), used internally to contain the matrix of the system of linear equations.
- * IDIMM is the first dimension of PHI, i.e., PHI(IDIMM, N).
- IDIMN is the first dimension of AM, i.e., AM(IDIMN,N).

Discussion

If the user wishes to minimize $\sum_{n=1}^{M} w_n \left[Y_n - F(X_{n'}) \right] \frac{2}{\varepsilon} w_1 = 0$, modify the PHI and Y arrays as follows:

$$\begin{array}{c} \text{PHI} & \sqrt{w_1 \; \text{PHI}(1,1)} \; \; \sqrt{w_1 \; \text{PHI}(1,2)} \; \text{...} \; \; \sqrt{w_1 \; \text{PHI}(1,N)} \\ \sqrt{w_2 \; \text{PHI}(2,1)} \; \; \text{...} \; \; & \\ \sqrt{w_M \; \text{PHI}(M,1)} \; \; & \\ \sqrt{w_M \; \text{PHI}(M,1)} \; & \\ \text{Y} = \begin{pmatrix} \sqrt{w_1 \; \text{Y}(1)} \\ \sqrt{w_2 \; \text{Y}(2)} \\ \sqrt{w_3 \; \text{Y}(3)} \\ & \\ \end{array} \right) \\ \sqrt{w_M \; \text{Y}(M)}$$

Sample Problem

Find the second degree polynomial $F=A_3\,x^2+A_2\,x+A_{16}$ which best fits the following data in the least squares sense, where $M=9_6\,N=3_5\,\text{MT}^2-1_6$

```
X = -4., -3., -2., -1., 0., 1., 2., 3., 4.

Y = 2., -3., -6., -7., -6., -3., 2., 9., 18.
```

Solution is $F = X^2 + 2X - 6$,

Sample Solution

```
NEW FILE NAME--EXAMPLE
READY
10 COMMON PHI(9,3),X(9),A(3),RW(27)
20 COMMON AM(3,3), Y(9), YA(9), NS(1)
30 DATA M.N.NT.NS/9.3.1.9/
40 INPUT, (X(1), I=1,M)
50 INPUT, (Y(I), I=1,M)
60 CALL PHII(M,N)
70 CALL LSQMM(PHI,Y,A,RW,M,N,NT,NS,AM,9,3)
80 D0 40 I=1.M
90 YA(1)=0.0
100 DØ 30 J=1.N
110 30 YA(I)=YA(I)+A(J)*PHI(I,J)
120 40 CONTINUE
130 PRINT 100
140 100 FØRMAT("
150 4 ")
                                    F(X)
                                                Y-F(X)
                                                                 A(N)
170 DØ 50 I=1.N
180 50 PRINT 60,X(1),YA(1),RW(1),A(1)
190 60 FØRMAT(4E13-4)
200 K=N+1
210 DU 70 I=K.M
220 70 FRINT 80,X(1),YA(1),RW(1)
230 80 FØRMAT(3E13.4)
240 STØP
250 END
260 SUBROUTINE PHIL(M,N)
270 COMMON PHI(9,3),X(9)
280 70 10 I=1,M
290 10 PHI(1,1)=1.0
300 IF(N-2) 40,15,15
310 15 DØ 30 I=1.M
320 DØ 20 J=2,N
330 80 PHI(I,J)=X(I)++(J-1
340 30 CONTINUE
350 4C RETURN
e ENI
RUN
```

EXAMPLE

7-4., -3., -6., -7., -6., -3., 2., 9., 18.

	X	FCXS	Y-F(X)	A(N)
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0.		-0.6000E+01	0•	
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0.0	10+3000	0.2000E+01	0•	
0.0	300E+01	9-9000E+01	0.	
0 • 4	400 .+01	0.1800E+12	0•	

APPENDIX B

INPUT-OUTPUT DESCRIPTION

INPUT-OUTPUT DESCRIPTION

PROGRAM NAME - SPIN-73

CODING DATE - July 1973

<u>PURPOSE</u> - Predict the aerodynamic coefficients of spin stabilized projectiles at Mach numbers for 0.0 to 5.0.

Inputs to the program are the projectile physical dimensions, projectile mass properties, gun bore diameter and twist, and the local air temperature.

INPUTS

D

Card No. 1 (See Note D)

IBM CARD COL	VARIABLE	
1 - 7	VL	Projectile length - calibers
8 - 14	VN	Ogive length - calibers
15 - 21	VB	Boattail length - calibers
22 - 28	VCG	Center of gravity - calibers for nos
29 - 35	DM BD_B	Diameter Me'Plat - calibers
36 - 42	BD B	Rotating band diameter - calibers
43 - 49	OR ^B	Ogive radius - calibers
50 - 56	BOOM	Boom length - calibers
57 – 80	NTITLE	Descriptor
Card No. 2 (See	Note C)	
1 - 7	DIA	Projectile diameter - inches 2
8 - 14	AX	Axial inertia - inches lb-in ²
15 - 21	TR	Transverse inertia - inches lb-in ²
22 - 28	WGT	Projectile weight - 1bs.
29 - 35	TWIST	Gun twist - cal/turn
36 - 42	$TFMP_{D}$	Air temperature - °F
43 - 49	$\mathtt{DGUN}_{\mathbf{A}}^{\mathbf{B}}$	Gun bore diameter - inches
50 - 56	$\mathtt{NAUTO}^{\mathbf{A}}$	O Uses input dimensions
		l Automatic dimensions
DD not and to	1 00 141	
BD set equal to DM set equal to		
OR set equal to		t ogiva)
ok set equal to	= (-vn-) (secan	t ogive)
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		puts are changed
BD set equal to		
OR set equal to		
DGUN set equal t	O DIA	
If aero estimate	s are only requ	irement

76

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Repeat cards 1 and 2 to stack cases

OUTPUTS

- Organization designation Line 1
- Line 2 - Description of item being estimated
- Title line projectile dimensions Line 3
- Projectile dimensions Line 4
- Title line projectile physical properties, gun properties Line 5 air temperature and density
- Projectile physical properties, gun properties, air temperature Line 6 and density
- Line 7 'Aerodynamic Coefficients'
- Line 8 Title line - Mach No., etc.
- Zero yaw axial force coefficient Line 9 Cxo
- Yaw axial force coefficient per sin CX2
 - CNA - Normal force coefficient derivative per $\sin \alpha$
 - CMA - Pitching moment coefficient derivative per sin a
 - CPN - Normal force center of pressure - calibers for nose
 - CYP - Magnus force coefficient derivative per $\sin \alpha$
 - CNPA - Zero yaw Magnus moment coefficient derivative per $\sin \alpha$
 - Cubic Magnus moment coefficient derivative per $\sin^3 \alpha_{5-}$ CNPA3
 - CNPA5 - Quintic Magnus moment coefficient derivative per sin a
 - Center of pressure of Magnus force at 1° yaw or less CPF1
 - calibers from nose
 - Center of pressure of Magnus force at 5° yaw, calibers CPF5 from nose
 - CNPA-5 5° Secant slope of Magnus moment coefficient
 - derivative (at 5 $^{\circ}$ yaw) per sin α
 - Cmq - Damping moment coefficient
 - Spin deceleration coefficient C1p

Line 10 -'Stability Analysis'

The state of the s

- Gyroscopic stability factor GYRO
- Dynamic stability factor at 1° yaw SBAR
- Dynamic reciprocal factor at 1° yaw RECIP
- Dynamic stability factor at 5° yaw SBAR5
- Dynamic reciprocal factor at 5° yaw RECIP5
- SPIN Spin rate, radians/second
- W1Nutation frequency, radians/second
- W2 Precession frequency, radians/second
- L1Nutation damping factor per foot @ 1° yaw
- L2Precession damping factor per foot @ 1° yaw
- Nutation damping factor per foot @5° yaw L1-5
- L2-5Precession damping factor per foot @ 5° yaw
- DELT Integration time step, seconds (20 per nutation)
- Dispersion factor per 5° first max yaw, mils DISP

APPENDIX C

PROGRAM LISTING

SPIN-73

```
| Sign(47), GPS(47), GPC1(17), GPC2(17), GPC2(17), GPC3(17), GPC3(
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               SPIN 200 SPI
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READCIR, 1007) DIA, AX, TR, MGT, THIST, TEMP, DGUN, NAUTO, NAERO, NSAUL, NNOL,
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2001 FORMATITAX, SHIPTAL, 19X, 5HMOSE , 8X, 9HBOAT TALL, 6X, 3HGG, 10X, 7HMFPLA .1 , 9X, 5HPAND , 11X, 5HNOSE , 11X, FHROOM /4X, 3KBX, 7HLE, GTH 3, 7X, 9HCFH .NOSE), 7 (AX, 9HG) AMPTER 3, HX, 6HR, DIUS, 10X, 6HLENGTH )
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      IME GE-400 SIMIES - FORTURY ASA (MIPC)
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13 ABSTRACT			
The SPINNER computer program has b	een updated	to com	pute aerodynamic
coefficients for a wide variety of	-	-	_
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Improvements over the original pro	_		-
radius, meplat diameter and rotati	ng band diar	neter al	re accounted for
instead of assuming mean values.	Test cases a	are show	wn compar the
1969 SPINNER, the 1973 SPINNER and			-
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tions and sumple program outputs a	re given alo	ong witi	n the 1973 program
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